Sensitivity Analysis with the \mathbb{R}^2 -Calculus

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Causal Inference and DAGs

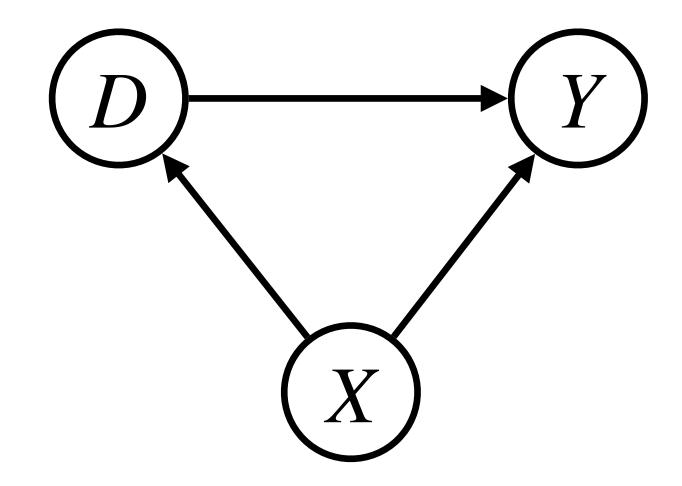
- Directed Acyclic Graph (DAG)
- Linear Structural Equation Model

$$X \Leftarrow \mathcal{E}_{X}$$

$$D \Leftarrow \beta_{DX} X + \mathcal{E}_{D}$$

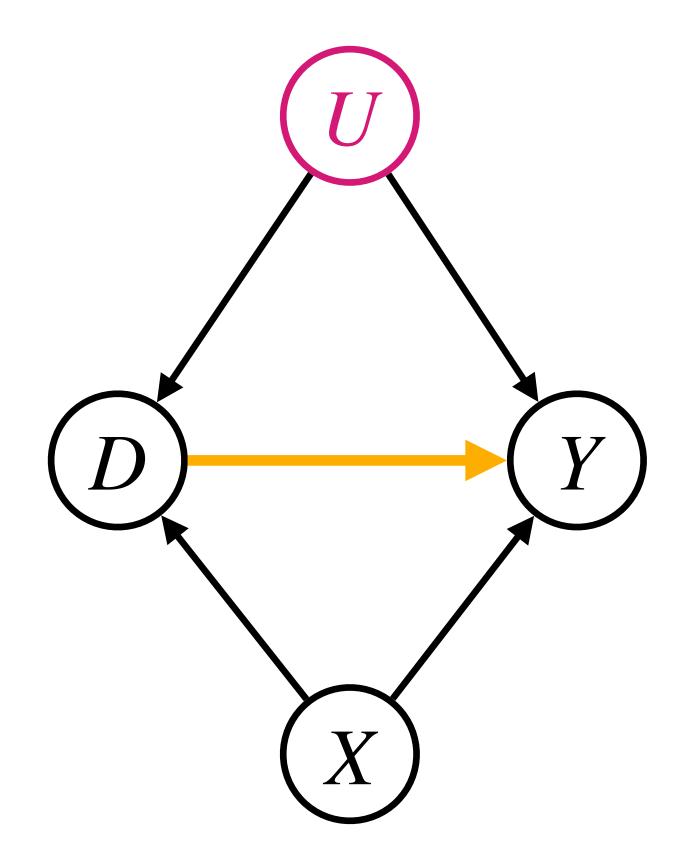
$$Y \Leftarrow \beta_{YD} D + \beta_{YX} X + \mathcal{E}_{Y}$$

• Goal: Estimate the causal effect of D on Y, i.e. estimate β_{YD} from data $(X_i, D_i, Y_i)_{i=1}^n$



Causal Inference and Sensitivity Analysis

- Goal: Estimate β_{YD}
- Assumptions:
 - Correction model specification, i.e. linearity
 - Correct DAG
 - No unmeasured confounders
- Sensitivity analysis explores how violations of assumptions affect estimation
- This work: focus on unmeasured confounders



Sensitivity Analysis - History

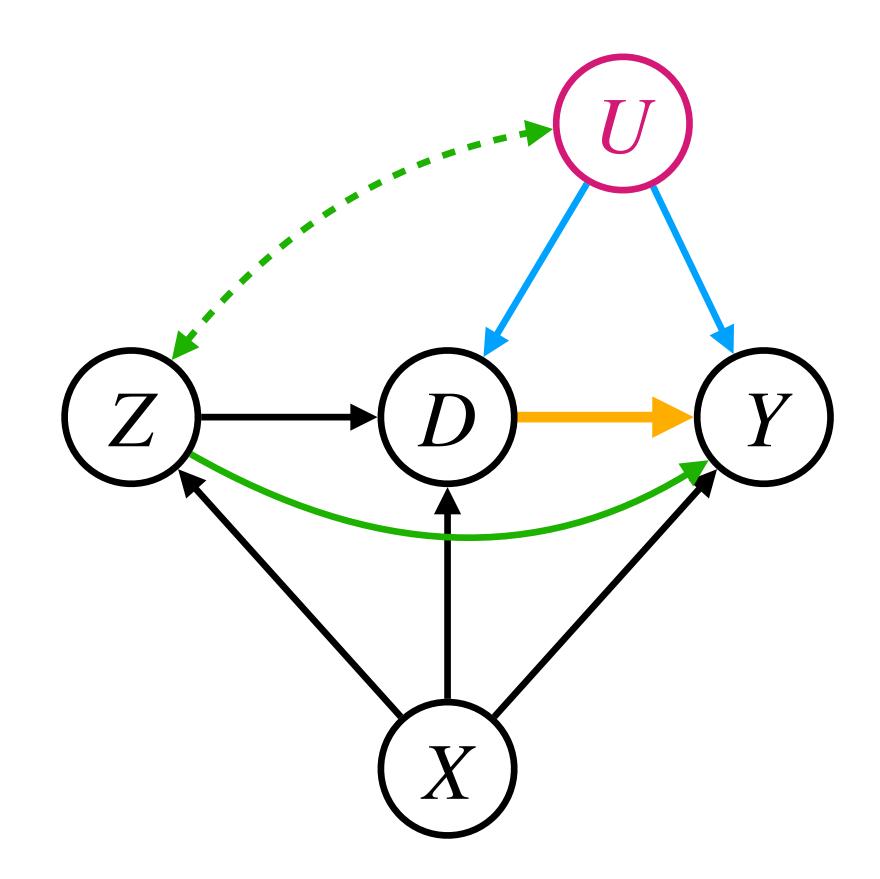
- Cornfield et al. (1959): Association between smoking and lung cancer
- Rosenbaum sensitivity model (Rosenbaum 1987), E-values (Ding and VanderWeele 2016), Marginal sensitivity model (Zhao et al. 2019, Dorn and Guo 2022), Instrumental variables (Altonji et al. 2005, Small 2007) and many more
- Lots of methods but hardly used in practice
- Reason: simplistic and unintuitive
- Proposal: constrained optimization → more flexibility and interpretability

Sensitivity Analysis - New Framework

- $(V_i, U_i)_{i=1}^n \sim \mathbb{P}_{V,U}$, but only $(V_i)_{i=1}^n$ observed
- Objective: $\beta(\theta, \psi)$
- θ are estimable parameters, i.e. only depend on \mathbb{P}_V
- ψ are sensitivity parameters, i.e. depend on $\mathbb{P}_{V,U}$
- Specify domain knowledge as constraints: $g(\theta, \psi) \leq 0$, $h(\theta, \psi) = 0$

$$\min / \max_{\psi} \beta(\hat{\theta}, \psi)$$
 subject to $g(\hat{\theta}, \psi) \leq 0$, $h(\hat{\theta}, \psi) = 0$.

Linear Model



Objective: $\beta = \beta_{Y \sim D|X,Z,U}$

Ordinary Least Squares (OLS)

$$\beta_{Y \sim D|X,Z} = \frac{\text{cov}(Y^{\perp X,Z}, D^{\perp X,Z})}{\text{var}(D^{\perp X,Z})}$$

Unbiased, if at least one of the arrows is absent.

Two-Stage Least Squares (TSLS)

$$\beta_{\text{TSLS}} = \frac{\text{cov}(Y^{\perp X}, Z^{\perp X})}{\text{cov}(D^{\perp X}, Z^{\perp X})}$$

Unbiased, if both of the arrows are absent.

Parameters θ and ψ : R-values

- Let Y be a random variable; X, W, Z be random vectors.
- Residual of Y after regressing out X denoted by $Y^{\perp X}$

$$R^2$$
-value:
$$R^2_{Y\sim X}:=1-\frac{\mathrm{var}(Y^{\perp X})}{\mathrm{var}(Y)}$$

Partial *R*-value :
$$R_{Y \sim X|Z} := corr(Y^{\perp Z}, X^{\perp Z})$$

$$R_{Y \sim X}^2 := 1 - \frac{\text{var}(Y^{\perp X})}{\text{var}(Y)}$$
 Partial R^2 -value: $R_{Y \sim X|Z}^2 := \frac{R_{Y \sim Z+X}^2 - R_{Y \sim Z}^2}{1 - R_{Y \sim Z}^2}$

Partial
$$f$$
-value :
$$f_{Y \sim X|Z} := \frac{R_{Y \sim X|Z}}{\sqrt{1 - R_{Y \sim X|Z}^2}}$$

R^2 -calculus

- (i) Independence: If $Y \perp \!\!\! \perp X$, then $R_{Y \sim X}^2 = 0$.
- (ii) Independent additivity: If $X \perp \!\!\! \perp W$, then $R_{Y \sim X+W}^2 = R_{Y \sim X}^2 + R_{Y \sim W}^2.$
- (iii) Decomposition of unexplained variance: $1 R_{Y \sim X+W}^2 = (1 R_{Y \sim X}^2)(1 R_{Y \sim W|X}^2)$
- (iv) Recursion of partial correlation:

$$R_{Y \sim X|W} = \frac{R_{Y \sim X} - R_{Y \sim W} R_{X \sim W}}{\sqrt{1 - R_{Y \sim W}^2 \sqrt{1 - R_{X \sim W}^2}}}$$

(v) Reduction of partial correlation: If X and W is one-dimensional and $Y \perp \!\!\! \perp W$, then

$$R_{Y \sim X|W} = \frac{R_{Y \sim X}}{\sqrt{1 - R_{X \sim W}^2}}$$

(vi) Three-variable restriction: If X and W is one-dimensional, then

$$f_{Y \sim X|W} \sqrt{1 - R_{Y \sim W|X}^2} = f_{Y \sim X} \sqrt{1 - R_{X \sim W}^2} - R_{Y \sim W|X} R_{X \sim W}.$$

All statements are also true when Z is partialed out, i.e. add " $\mid Z$ ".

Identifying objective eta in terms of heta and ψ

Causal effect: $\beta = \beta_{Y \sim D|X,Z,U}$

$$\beta = \beta_{Y \sim D|X,Z} - R_{Y \sim U|X,Z,D} f_{D \sim U|X,Z} \frac{\operatorname{sd}(Y^{\perp X,Z,D})}{\operatorname{sd}(D^{\perp X,Z})}$$

Sensitivity parameters ψ : $R_{Y \sim U|X,Z,D}$ and $R_{D \sim U|X,Z}$

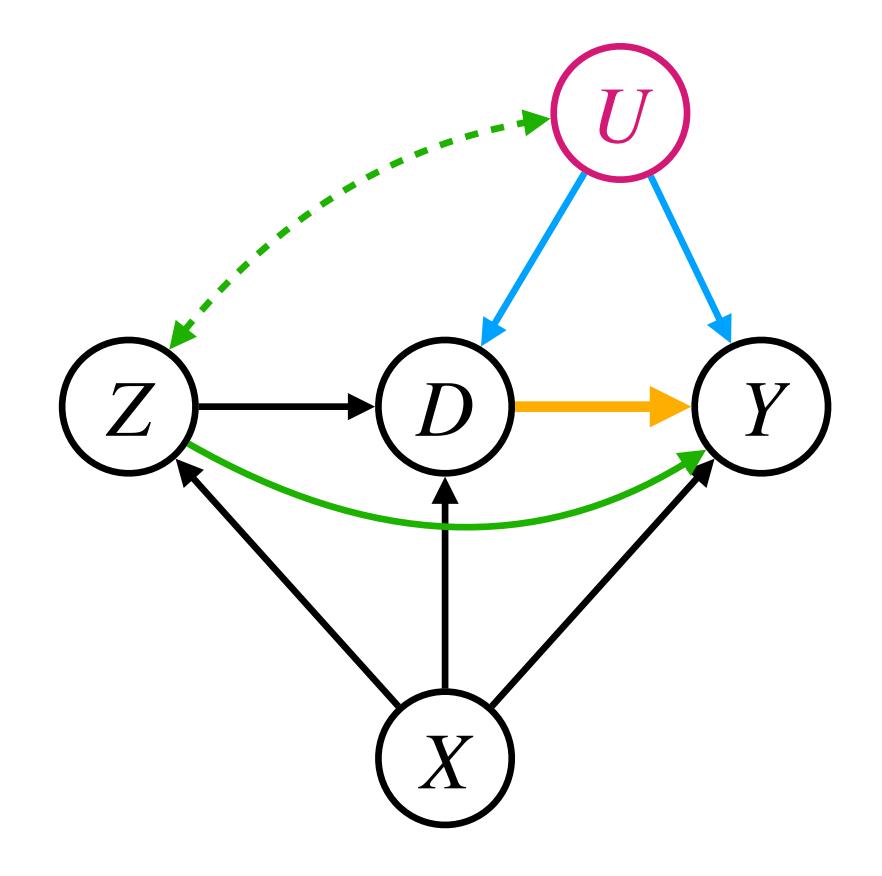
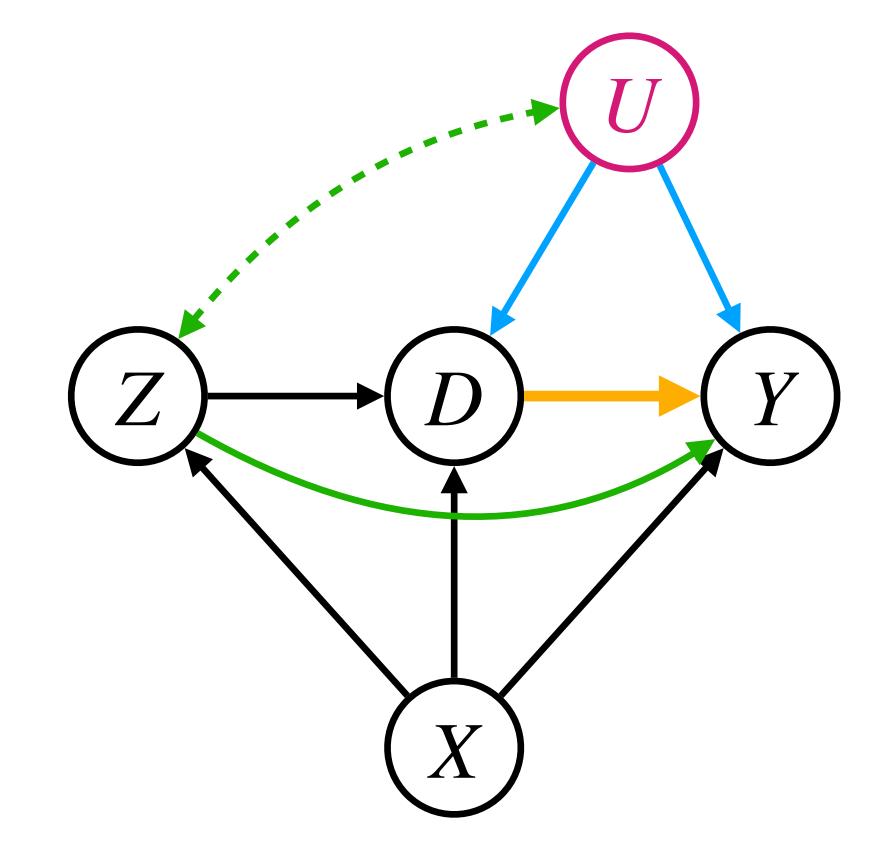


Table of Bounds

$U \rightarrow D$	$R_{D \sim U X,Z} \in [B_{UD}^l, B_{UD}^u]$
	$R_{D\sim U \tilde{X},\dot{X}_I,Z}^2 \leq b_{UD} R_{D\sim \dot{X}_J \tilde{X},\dot{X}_I,Z}^2$
U o Y	$R_{Y \sim U X,D,Z} \in [B_{UY}^l, B_{UY}^u]$
	$R^2_{Y \sim U \tilde{X}, \dot{X}_I, Z} \leq b_{UY} R^2_{Y \sim \dot{X}_J \tilde{X}, \dot{X}_I, Z}$
	$R_{Y \sim U \tilde{X}, \dot{X}_I, Z, D}^2 \leq b_{UY} R_{Y \sim \dot{X}_J \tilde{X}, \dot{X}_I, Z, D}^2$
$U \leftrightarrow Z$	$R_{Y \sim Z X,U,D} \in [B_{ZY}^l, B_{ZY}^u]$
	$R_{Z \sim U \mid \tilde{X}, \dot{X}_{-j}}^{2} \leq b_{UZ} R_{Z \sim \dot{X}_{j} \mid \tilde{X}, \dot{X}_{-j}}^{2}$
$Z \rightarrow Y$	$R_{Y \sim Z X,U,D} \in [B_{ZY}^l, B_{ZY}^u]$
	$R_{Y \sim Z X,U,D}^2 \le b_{ZY} R_{Y \sim \dot{X}_j \tilde{X},\dot{X}_{-j},Z,U,D}^2$



The bounds can be combined in any way.

Constraints $g(\theta, \psi) \leq 0$

- Direct bounds, e.g. $R_{D \sim U|X,Z} \in [-0.2, 0.4], R_{Y \sim U|X,Z,D}^2 \le 0.5$
- Assumption: $X = (\dot{X}, \tilde{X})$ such that $U \perp \!\!\! \perp \dot{X} \mid \tilde{X}, Z$
- Comparative bound, e.g. $R^2_{Y\sim U|\tilde{X},\dot{X}_{-j},Z} \leq 2\,R^2_{Y\sim\dot{X}_j|\tilde{X},\dot{X}_{-j},Z}$

The unmeasured confounder U can explain at most twice as much variance in Y than \dot{X}_j does - conditional on $(\tilde{X}, \dot{X}_{-i}, Z)$.

Constraints $g(\theta, \psi) \leq 0$ and $h(\theta, \psi) = 0$

•
$$\min / \max \beta_{Y \sim D|X,Z} - R_{Y \sim U|X,Z,D} f_{D \sim U|X,Z} \frac{\operatorname{sd}(Y^{\perp X,Z,D})}{\operatorname{sd}(D^{\perp X,Z})}$$
 subject to $(1), (2), (3)$

• Bounds:
$$R^2_{Y \sim U|\tilde{X},\dot{X}_{-i},Z} \le 2R^2_{Y \sim \dot{X}_i|\tilde{X},\dot{X}_{-i},Z}$$
 , $R_{D \sim U|X,Z} \in [-0.2,0.4]$ (1)

•
$$R_{Y \sim U|X,Z}^2 \stackrel{\text{(V)}}{=} \frac{R_{Y \sim U|\tilde{X},\dot{X}_{-j},Z}^2}{1 - R_{Y \sim \dot{X}_i|\tilde{X},\dot{X}_{-j},Z}^2}$$
 (2)

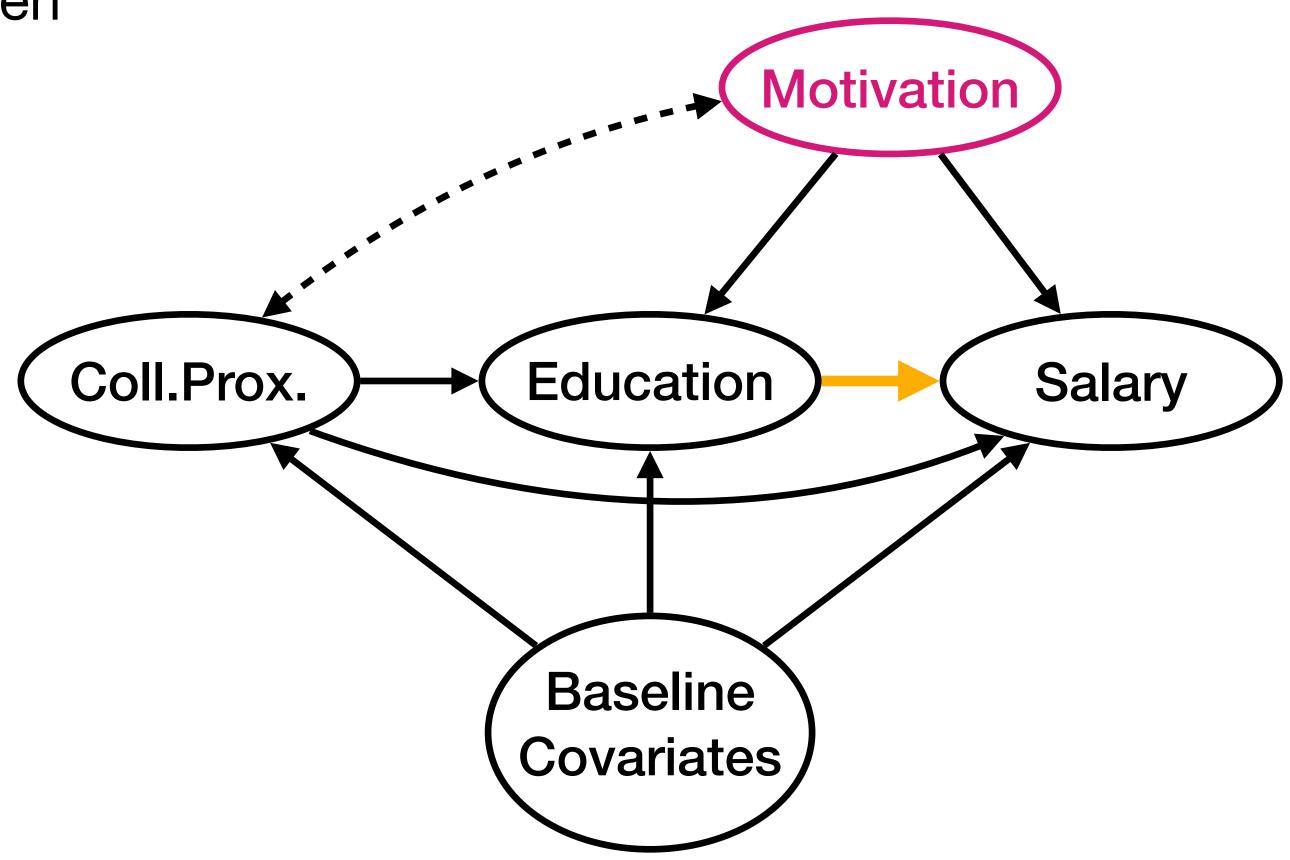
•
$$R_{Y \sim U|X,Z,D} \stackrel{\text{(iv)}}{=} \frac{R_{Y \sim U|X,Z} - R_{Y \sim D|X,Z} R_{D \sim U|X,Z}}{\sqrt{1 - R_{Y \sim D|X,Z}^2} \sqrt{1 - R_{D \sim U|X,Z}^2}}$$
 (3)

Optimization - Leveraging Monotonicity

- $a = R_{D \sim U|X,Z}$, $b = R_{Y \sim U|X,Z,D}$, $d = R_{Y \sim U|X,Z}$
- min/max $c_1 b \frac{a}{\sqrt{1 a^2}} c_2$, s.t. $a \in [-0.2, 0.4], d^2 \le c_3, b = \frac{d c_4 a}{\sqrt{1 c_4^2} \sqrt{1 a^2}}$
- Brute force grid search: create three-dimensional grid of (a, b, d)-values
- Adapted grid search:
 - For fixed a, b is monotone in d and the objective is monotone in b
 - One-dimensional grid of a-values
- $\mathcal{O}(m^3)$, but often $\mathcal{O}(m)$, where m is the number of points per grid dimension

Data Example

- National Longitudinal Survey of Young Men
- From 1966 until 1981
- 3010 individuals
- Y: log-earnings
- D: years of schooling
- X: years of labour force experience; indicators for living in the south, being black and living in a metropolitan area
- Z: growing up close to 4-year college

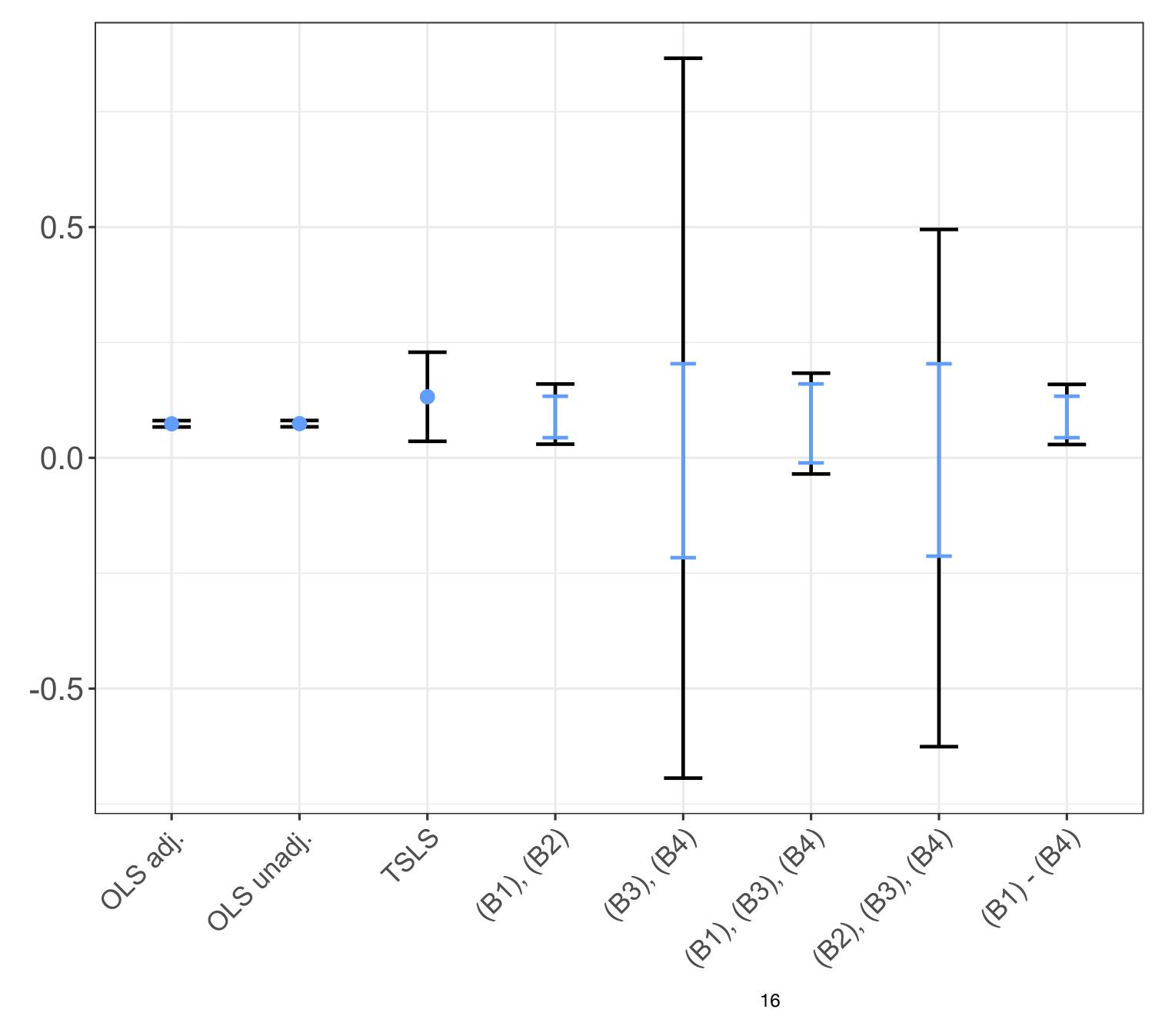


Sensitivity Analysis

- Partition covariates X: \dot{X} indicator for being black; \tilde{X} remaining covariates
- Assumption: $U \perp\!\!\!\perp \dot{X} \mid \tilde{X}, Z$
- User specified bounds:

(B1)
$$R_{D \sim U|\tilde{X},Z}^2 \le 4 \, R_{D \sim \dot{X}|\tilde{X},Z}^2$$
 (B2) $R_{Y \sim U|\tilde{X},Z,D}^2 \le 5 \, R_{Y \sim \dot{X}|\tilde{X},Z,D}^2$

(B3)
$$R_{Z \sim U \mid \tilde{X}}^2 \leq 0.5 \, R_{Z \sim \dot{X} \mid \tilde{X}}^2$$
 (B4) $R_{Y \sim Z \mid X, U, D}^2 \leq 0.1 \, R_{Y \sim \dot{X} \mid \tilde{X}, Z, U, D}^2$



(B1): $U \rightarrow D$

(B2): $U \rightarrow Y$

(B3): $U \leftrightarrow Z$ (B4): $Z \rightarrow Y$

Things I did not talk about

- Extension of the \mathbb{R}^2 -calculus to Hilbert spaces
- Multiple unmeasured confounders
- Confidence statements: Sensitivity intervals via bootstrap
- Additional visualization tools

Conclusion

- New Framework: Sensitivity analysis as optimization problem
- Introduction of the R^2 -calculus
- Sensitivity analysis in linear models with R-values (OLS and TSLS)
- Flexible and interpretable bounds
- Application on a dataset

Thanks for your attention!

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arXiv: https://arxiv.org/abs/2301.00040
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Website: https://tobias-freidling.onrender.com

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